

Czech Technical University in Prague

Faculty of Mechanical Engineering

Department of Technical Mathematics, Karlovo nám. 13, 121 35 Prague 2

Mathematics I, level Beta - Requirements for exams in academic year 2018/19

- 1) Vector space, linearly dependent and linearly independent vectors, dimension, basis, subspace. Special spaces \mathbb{R}^n , \mathbb{E}_n and $V(\mathbb{E}_n)$. Operations with vectors in $V(\mathbb{E}_n)$: addition, subtraction, multiplication of a vector by a scalar, product (scalar and vector) of two vectors.
 - Matrix of the type $m \times n$, matrices: transposed, upper triangular, square, identity.
- 2) Equality of two matrices, operations with matrices (the sum, difference, multiplication by a scalar, multiplication of two matrices). Rank of a matrix. How to find the rank of a matrix.
 - Determinant of a square matrix. Properties and calculation of determinants. Regular and singular matrix. Inverse matrix, Conditions for the existence and calculation of the inverse matrix.
- 3) System of linear algebraic equations, its matrix form. Gauss' elimination. Frobenius' theorem. Existence and uniqueness of solutions of homogeneous and non-homogeneous systems, the structure of the set of all solutions.
 - Cramer's rule. Eigenvalue and eigenvector of a square matrix, geometrical interpretation. Characteristic equation of a square matrix. Calculation of eigenvalues and eigenvectors of a matrix (in the exam up to 3×3 matrices).
- 4) Set of real numbers \mathbb{R} , extended set of real numbers \mathbb{R}^* , operations and ordering in set \mathbb{R}^* . Types of neighbourhoods of points in \mathbb{R}^* . A sequence of real numbers, properties of sequences: upper bounded, lower bounded, bounded, increasing, decreasing. A subsequence.
 - Limit of a sequence. Basic theorems on limits of sequences, calculation of limits of simple sequences.
- 5) Survey and completion of notions from elementary mathematics: Function of one real variable, domain of definition, range, graph. Restriction of a function. Function even, odd, periodic. Composite function. Inverse function. Function upper bounded, lower bounded, bounded, increasing, decreasing, non–increasing, non–decreasing, monotone, strictly monotone. Survey of basic elementary functions: power function, polynomials, exponential, logarithmic, trigonometric, inverse trigonometric.
 - Limit of a function (finite and infinite, at a finite point or at infinity). One–sided limits. Basic theorems on limits. Calculation of simple limits.
 - Continuity of a function (at a point or on an interval), right and left continuity. Theorems on continuity of a sum, difference, product and ratio of two functions. Continuity of a composite function and an inverse function. Darboux's theorem and theorem on existence of extreme values of a continuous function on a bounded closed interval.
- 6) Derivative of a function at a point, one-sided derivatives, improper derivative. Geometrical and physical interpretation of derivative. Equation of the tangent line to the graph of a function y = f(x) at given point. Differential of a function at a point, its geometrical sense, application to approximate calculation of function values. Approximate solution of the equation f(x) = 0 (informatively).
 - Derivative of a sum, difference, product, fraction. Derivatives of elementary functions. Derivative of a composite function (the chain rule) and an inverse function. Applications to simple examples. Higher order derivatives.

The mean value theorem, geometrical meaning. L'Hospital's rule. Existence of derivative implies continuity.

- 7) Consequences of the sign of the derivative for the behaviour of a function on an interval. Local extrema of a function, application of the first and the second derivative. How to find local extrema. Global extrema of a continuous function on an interval.
- 8) Functions concave up (convex) and concave down (concave). Point of inflection. Application of the second derivative. How to find points of inflection.
 - Asymptotes. Investigation of the behaviour of a function, sketching the graph.
- 9) Curvature, osculation circle. Taylor's polynomial (MacLaurin's polynomial) of the *n*-th degree of function *f* at a point. Coefficients of Taylor's polynomial. Approximation of simple functions by Taylor's polynomials.
 - Antiderivative, indefinite integral. Existence of an antiderivative and an indefinite integral on an interval. Basic indefinite integrals. Integration by parts.
- **10**) Integration by substitution. Application to simple examples.
 - Rational functions introduction. Integration of a rational function with polynomial of at most 2nd degree in the denominator.
- 11) Integration of functions of the type $\sin^m x \cdot \cos^n x$.
 - Definite (Riemann's) integral, its geometrical and physical interpretation, basic properties. Newton–Leibniz formula. Integration by parts in definite (Riemann's) integral.
- **12**) Integration by substitution in definite integral. Geometrical applications of definite integral: area of a surface, volume of a rotationally symmetric body, length of a curve.
 - Riemann's integral as a function of the upper limit.

Topics not included in the level Beta (with respect to Alpha)

- Estimation of the error (remainder) for the Taylor's polynomial.
- Integrals with the n-th root of the rational function.
- Integrals of rational functions with a polynomial of the order three (and higher) in the denominator.
- Improper integrals.